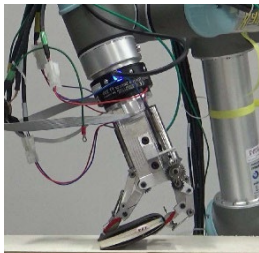


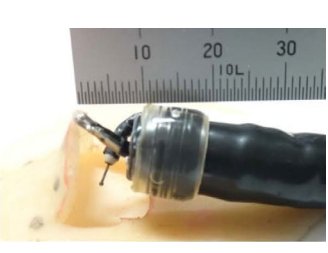
Dexterous Manipulation



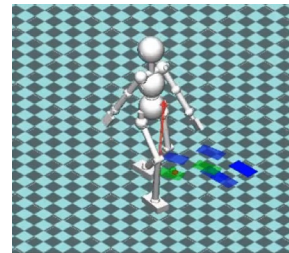
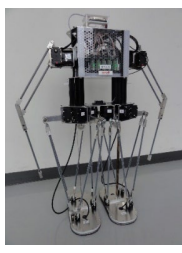
Human hand analysis / General-purpose robot hand for picking



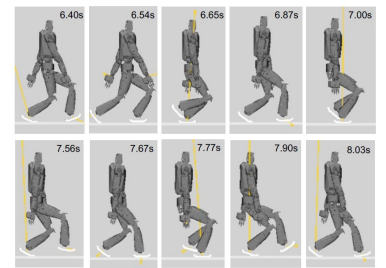
Flexible Endoscopic Surgical Robot



Humanoid / Bipedal Robots



Fall avoidance



Trajectory generation & tracking control

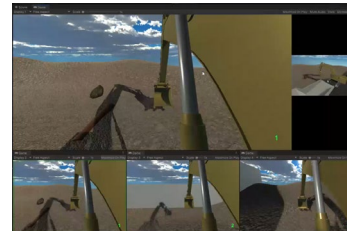
Teleoperation Systems



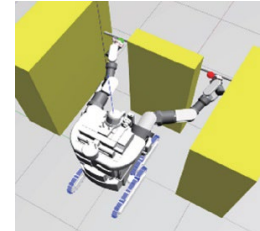
Teleoperation system with multiple screens



Integration of Robot Autonomy and Teleoperation

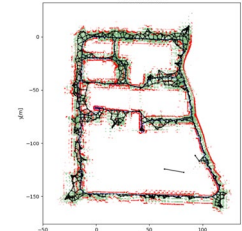


Simultaneous control of multiple construction robots



Decommissioning work in a narrow space

Mobile Robots

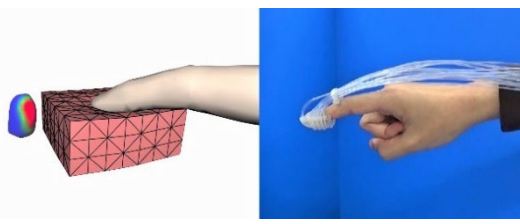
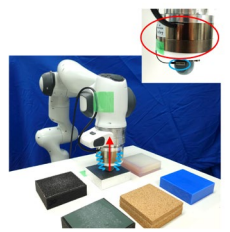


Autonomous map generation

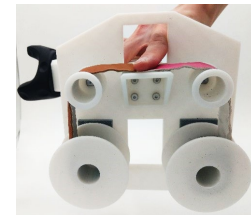
Haptic Interface / Haptic VR



Haptic telecommunication system



Wearable tactile display



Tactile display using real materials

